

# Tight Bounds on Approximating Minimum Cuts in Insertion-Only Streaming Model

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## Graphs in the Insertion Streaming Model

We begin with a set of nodes  $V = \{1, \dots, n\}$ . One by one, we are given a sequence or "stream" of  $m$  edges  $e = (u, v)$  where  $u, v \in V$ . The goal is to minimize the amount of space used while the stream is coming in.

### Definition: Cut

A cut in a graph is a partition  $(S, V \setminus S)$  of the graph into two non-empty sets.

### Definition: Minimum Cut

The minimum cut is a cut  $(S', V \setminus S')$  with the fewest number of crossing edges.

# Motivation

- Computing the value of a minimum cut in a graph is an incredibly important problem.
- The streaming model is a very practical model for real-world situations.
- In real world applications, it is usually sufficient to get a good approximation.

# Approximation Definitions

## $(1 + \epsilon)$ -Approximation to Cut Value

Given cut value  $\lambda$ , we say  $\lambda'$  is a  $(1 + \epsilon)$ -approximation to  $\lambda$  if

$$(1 - \epsilon)\lambda \leq \lambda' \leq (1 + \epsilon)\lambda$$

## $(1 + \epsilon)$ -Cut Sparsifier

Given graph  $G = (V, E)$ , we say graph  $H = (V, E')$  is a  $(1 + \epsilon)$ -cut sparsifier of  $G$  if, with high probability,

$$(1 - \epsilon)\lambda_G(S, V \setminus S) \leq \lambda_H(S, V \setminus S) \leq (1 + \epsilon)\lambda_G(S, V \setminus S)$$

holds  $\forall S \subset V, S \neq \emptyset$ .

## Theorem 1 (Black Box)

There exists a single-pass algorithm  $\mathcal{A}$  that returns a for-all  $(1 + \epsilon)$  cut-sparsifier for a graph with  $O(\text{poly } n)$  edge weights in the insertion-only streaming model using  $\tilde{O}(\frac{n}{\epsilon^2})$  space. [AGM12]

## Theorem 2

Any single-pass algorithm that returns a  $(1 + \epsilon)$ -approximation to the minimum cut problem in the insertion-only streaming model requires at least  $\Omega(n \log(1/\epsilon))$  bits. [AG09]

## Result 1

There exists a single-pass algorithm that returns a  $(1 + \epsilon)$ -approximation to the minimum cut problem on graphs with  $O(\text{poly } n)$  edge weights in the insertion-only streaming model using  $\tilde{O}(\frac{n}{\epsilon})$  space.

## Result 2

Any single-pass algorithm that computes a  $(1 + \epsilon)$ -approximation to the minimum cut of a graph in an insertion-only stream uses at least  $\Omega(\frac{n}{\epsilon})$  bits of space.

# Important Sparsifier Properties

## Mergeability

Let  $H_1$  and  $H_2$  be  $(1 + \epsilon)$  cut-sparsifiers of graphs  $G_1$  and  $G_2$  on the same vertices. Then,  $H_1 \cup H_2$  is a  $(1 + \epsilon)$  cut-sparsifier of graph  $G_1 \cup G_2$ .

## Composability

Let  $H$  be a  $(1 + \epsilon)$  cut-sparsifier of  $H_1$  and  $H_1$  be a  $(1 + \epsilon)$  cut-sparsifier of  $G$ . Then,  $H$  is a  $(1 + \epsilon)^2 \approx (1 + 2\epsilon)$  cut-sparsifier of  $G$ .

# Existing Algorithm [McGregor14]

- 1 Partition stream into  $t = m\epsilon^2/n$  groups, each with  $n/\epsilon^2$  edges
- 2 Let  $G_i^0$  denote the  $i$ -th group of edges, recursively define

$$G_i^j = G_{2i-1}^{j-1} \cup G_{2i}^{j-1}$$

- 3 Build sparsified graphs for each of the  $G_i^j$ s:

$$H_i^0 = G_i^0, H_i^j = \mathcal{A}(H_{2i-1}^{j-1} \cup H_{2i}^{j-1})$$

where  $\mathcal{A}(G)$  denotes running the black box algorithm on  $G$  with an approximation value of  $\delta$  which we will set.



## Existing Algorithm (cont.)

From the mergeability and composability properties of sparsifiers, we see that  $H_1^{\log t}$  is a  $(1 + \delta)^{\log t}$  sparsifier of  $G$ . Now, suppose we pick  $\delta = \frac{\epsilon}{2 \log t}$ . Thus,

$$(1 + \delta)^{\log t} \leq \exp(\delta \log t) = \exp(\epsilon/2) \leq 1 + \epsilon$$

where the first and second inequalities come from the fact that  $1 + x \leq e^x$  for all  $x$  and  $e^x \leq 1 + 2x$  for  $x \in [0, 1]$ , respectively.

Thus, we obtain a  $(1 + \epsilon)$  cut-sparsifier. The space complexity of the algorithm is  $\tilde{O}(\frac{n}{\epsilon^2})$ .

# New Black Box

The space bound of the algorithm above depends entirely on the space bound of the black box. Thus, if we can use a better black box, we can directly improve the algorithm's space bound!

## Theorem 3 (Better Black Box)

There exists an algorithm  $\mathcal{K}$  that returns a graph  $H$  with  $\tilde{O}(n/\epsilon)$  edges in  $\tilde{O}(mn)$  time that gives a **"for-each"**  $(1 + \epsilon)$  cut-sparsifier. [CGPSSW18]

# "for-all" vs. "for-each" Sparsifiers

"for-all" sparsifiers guarantees that, with high probability, **ALL** cuts will be preserved within a factor of  $(1 + \epsilon)$ .

"for-each" sparsifiers guarantee that **EACH** cut is preserved within a factor of  $(1 + \epsilon)$  with high probability.

Mergability and composability hold for both sparsifier types!

# Problem :(

We can't apply the new black box directly! We need to somehow bound the number of cuts we're interested in looking at to a polynomial amount.

## Definition: $\alpha$ -minimal cut

An  $\alpha$ -minimal cut is a cut of value within a multiplicative factor of  $\alpha$  of the minimum.

## Karger's Cut Counting Lemma

In any graph, the number of  $\alpha$ -minimal cuts is  $\leq (2n)^{2\alpha}$ .

All of these minimal cuts can be obtained with high probability by running Karger's Recursive Contraction Algorithm, which can be done in  $O(m \log(n^2/m))$  space.

# Our Algorithm

- 1 Partition stream into  $t = m\epsilon/n$  groups, each with  $n/\epsilon$  edges
- 2 Let  $G_i^0$  denote the  $i$ -th group of edges, recursively define

$$G_i^j = G_{2i-1}^{j-1} \cup G_{2i}^{j-1}$$

- 3 Build sparsified graphs for each of the  $G_i^j$ s:

$$H_i^0 = G_i^0, H_i^j = \mathcal{K}(H_{2i-1}^{j-1} \cup H_{2i}^{j-1})$$

where we run  $\mathcal{K}$  on a value  $\epsilon' = \frac{\epsilon}{2^{\log t}}$ .

- 4 Use  $\mathcal{A}$  to construct a "for-all" 1.1 cut-sparsifier
- 5 Retrieve all 1.1-minimal cuts via Recursive Contraction and store them
- 6 Query  $H_1^{\log t}$  for values of all the stored cuts and return the smallest value

# Our Algorithm (Analysis)

By the same analysis as before,  $H_1^{\log t}$  is a "for-each"  $(1 + \epsilon)$  cut-sparsifier of  $G$ .

The minimum cut  $\lambda$  has value at most  $1.1\lambda$  in the "for-all" cut sparsifier. By retrieving all 1.1-minimal cuts, we guarantee that we also retrieve the minimum cut. Since  $H_1^{\log t}$  is a "for-each"  $(1 + \epsilon)$  cut-sparsifier, it preserves with high probability, say  $1 - 1/n^4$ , the value of each cut we're interested in.

Let  $\mathcal{C} = \{C_1, \dots, C_k\}$  be the set of 1.1-minimal cuts returned by the contraction procedure. Let  $A$  be the event that we choose the wrong cut in this set to take as the source of the minimum cut value. Denote the event that cut  $C_i$  is not preserved as  $E_{C_i}$ . Then,

$$\Pr(A) \leq \Pr(E_{C_1} \cup \dots \cup E_{C_k}) \leq \sum_{i=1}^{n^{2.2}} \Pr(E_{C_i}) = \sum_{i=1}^{n^{2.2}} n^{-4} \leq 1/n$$

Thus, the probability that we approximate the minimum cut correctly is at least  $1 - 1/n$ .

## Our Algorithm (Analysis cont.)

The space bound analysis follows almost immediately from the analysis of the algorithm in McGregor's survey paper. We only need two sparsifiers for each of the  $\log t \leq \log n$  levels, and each sparsifier takes  $\tilde{O}(n/\epsilon)$  space. Thus, we have an overall space bound of  $\tilde{O}(n/\epsilon)$ .






Are similar results possible in dynamic streams? Hopefully so...

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# The End!

Thanks for listening :)