Visibility Graphs of Staircase Polygons



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<u>Mentor:</u> Prof. James Abello Work supported by NSF grant CCF-1559855.

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- Two vertices of the polygon are called <u>internally visible</u> if the closed line segment between them is either an edge of the polygon or lies entirely in the interior of the polygon (Abello et al).
- The <u>visibility graph</u> of a polygon is a graph whose vertex set is the same as the vertex set of a polygon and whose edges are the straight-line segments between internally visible vertices.



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- Define the <u>hook</u> of a cell to be the collection of cells that includes the chosen cell with all the cells above it and all the cells to the right
- <u>Mate cells</u> with respect to 7
- A tableau is <u>balanced</u> if the value of every cell lies in between every pair of mate cells in its hook



Local Maxima Rule

- Obtain the Local Maxima (Minima) Tableau from a Balanced Tableau
- It is a collection of subdiagonal entries of an adjacency matrix of a graph



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Problem Statement: <u>Input:</u> A balanced tableau T_n <u>Output:</u> Build a staircase polygon s.t. its visibility graph is isomorphic to localMax (T_n)

- The problem is known to be PSPACE
- We also want to know whether it is NP or P

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- Top Down Extension:
 - Build a visibility graph for the balanced tableau without the last row



- Top Down Extension:
 - Build a visibility graph for the balanced tableau without the last row
 - Inductively construct the graph with the last row





References:

• [1] Abello et al, Visibility Graphs of Staircase Polygons and the Weak Bruhat Order, I: from Visibility Graphs to Maximal Chains*. Discrete & Computational Geometry. 1995. 331-358.